

# Package ‘gplsim’

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**Type** Package

**Title** Spline Estimation for GPLSIM

**Version** 1.0.0

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**Description** We provides functions that employ splines to estimate generalized partially linear single index models (GPLSIM), which extend the generalized linear models to include nonlinear effect for some predictors. Please see Y. (2017) at [doi:10.1007/s11222-016-9639-0](https://doi.org/10.1007/s11222-016-9639-0) and Y., and R. (2002) at [doi:10.1198/016214502388618861](https://doi.org/10.1198/016214502388618861) for more details.

**License** GPL-2

**Encoding** UTF-8

**Depends** R (>= 3.6.0)

**Imports** mgcv, stats, minpack.lm

**LazyData** true

**RoxygenNote** 7.2.1

**Suggests** testthat (>= 3.0.0)

**Config/testthat/edition** 3

**NeedsCompilation** no

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## Contents

add_sim_bound . . . . .	2
air . . . . .	3
generate_data . . . . .	4
gplsim . . . . .	4

plot_si . . . . .	7
Predict.matrix.tr.smooth . . . . .	7
print.summary.gplsim . . . . .	8
si . . . . .	9
smooth.construct.tr.smooth.spec . . . . .	10
summary.gplsim . . . . .	10

<b>Index</b>	<b>11</b>
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add_sim_bound	<i>function dedicated to add simulation standard error bound, in development draw the bound to current plot</i>
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### Description

function dedicated to add simulation standard error bound, in development draw the bound to current plot

### Usage

```
add_sim_bound(
  data,
  family = gaussian(),
  M = 200,
  n = 1000,
  true.theta = c(1, 1, 1)/sqrt(3)
)
```

### Arguments

data	a list of simulated data
family	default is gaussian()
M	number of simulations
n	sample size
true.theta	the true coefficients

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air *dataset from an environmental study.*

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### Description

This dataset contains four variables: The concentration of the air pollutant ozone, wind speed, temperature and radiation. All of them are daily measurements for 111 days. Usually the concentration of the air pollutant ozone serves as the response variable while the other three are predictors.

### Usage

```
data("air")
```

### Format

A data frame with 111 observations on the following 4 variables.

ozone a numeric vector in cube root ppb

radiation a numeric vector in langley

temperature a numeric vector in degrees F

wind\_speed a numeric vector in mph

### Examples

```
data(air)
y=air$ozone           # response
X=as.matrix(air[,3:4]) # single index term ;
Z=air[,2]             # partially linear term ;

result <- gplsim(y,X,Z=Z,family = gaussian,k=10)
result$theta
result$coefficients
summary(result)

# Or you can try different spline basis
result <- gplsim(y,X,Z=Z,family = gaussian,bs="tp",k=10)
result$theta
result$coefficients
summary(result)
```

---

generate_data	<i>Data generation function for simulation and demonstration A sine-bump setting has been employed.</i>
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---

### Description

Data generation function for simulation and demonstration A sine-bump setting has been employed.

### Usage

```
generate_data(  
  n,  
  true.theta = c(1, 1, 1)/sqrt(3),  
  family = "gaussian",  
  ncopy = 1  
)
```

### Arguments

n	sample size
true.theta	true single-index coefficients, default is $c(1,1,1)/\sqrt{3}$ for setting 1 and $c(1,2)/\sqrt{5}$ for other settings
family	chose from "gaussian", "binomial" or "poisson".
ncopy	generates multiple copies of data for Monte Carlo simulations

### Value

X single index predictors  
 Y response variables, a list  
 Z partial linear predictor(s)  
 single\_index\_values single index term

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gplsim	<i>Function to fit generalized partially linear single-index models via penalized splines</i>
--------	---

---

### Description

This function employs penalized spline (P-spline) to estimate generalized partially linear single index models, which extend the generalized linear models to include nonlinear effect for some predictors.

This function add formula interface to gplsim function

**Usage**

```

gplsim(...)

## Default S3 method:
gplsim(
  Y = Y,
  X = X,
  Z = Z,
  family = gaussian(),
  penalty = TRUE,
  profile = TRUE,
  user.init = NULL,
  bs = "ps",
  ...
)

## S3 method for class 'formula'
gplsim(
  formula,
  data,
  family = gaussian(),
  penalty = TRUE,
  profile = TRUE,
  user.init = NULL,
  bs = "ps",
  ...
)

```

**Arguments**

...	includes optional arguments user can pass to <code>mgcv::gam</code> or <code>glm</code> , such as <code>k</code> , which is the dimension of the basis of the smooth term and <code>m</code> , which is the order of the penalty for the smooth term. Others include: <code>scale</code> The optional argument <code>scale</code> is a numeric indicator with a default value set to -1. Any negative value including -1 indicates that the scale of response distribution is unknown, thus need to be estimated. Another option is 0 signaling scale of 1 for Poisson and binomial distribution and unknown for others. Any positive value will be taken as the known scale parameter. <code>smooth_selection</code> The optional argument <code>smooth_selection</code> is another character variable that specifies the criterion used in the selection of a smoothing parameter. The supported criteria include "GCV.Cp", "GACV.Cp", "ML", "P-ML", "P-REML" and "REML", while the default criterion is "GCV.Cp".
Y	Response variable, should be a vector.
X	Single index covariates.
Z	Partially linear covariates.
family	A family object: a list of functions and expressions for defining link and variance functions. Families supported are binomial, gaussian. The default

	family is gaussian.
penalty	Whether use penalized splines or un-penalized splines to fit the model. The default is TRUE.
profile	profile is a logical variable that indicates whether the algorithm with profile likelihood or algorithm with NLS procedure should be used. The default algorithm is set to algorithm with profile likelihood.
user.init	The user.init is a numeric vector of the same length as the dimensionality of single index predictors. The users can use this argument to pass in any appropriate user-defined initial single-index coefficients based on prior information or domain knowledge. The default value is NULL.
bs	bs is a character variable that specifies the spline basis in the estimation of unknown univariate function of single index. Default is P-splines.
formula	A model formula;
data	A data matrix containing the variables in the formula.

### Details

For formula method, see `?gplsim.formula`

### Value

theta Estimation of Theta

coefficients the coefficients of the fitted model. Parametric coefficients are first, followed by coefficients for each spline term in turn.

... See GAM object

theta Estimation of Theta

coefficients the coefficients of the fitted model. Parametric coefficients are first, followed by coefficients for each spline term in turn.

... See GAM object

### Examples

```
# parameter settings
n=200
true.theta = c(1, 1, 1)/sqrt(3)
# Gaussian case
# This function generate a plain sin bump model with gaussian response.
data <- generate_data(n,true.theta=true.theta,family="gaussian")
y=data$Y      # continous response
X=data$X      # single index term ;
Z=data$Z      # partially linear term ;

result <- gplsim(y,X,Z,family = gaussian)
result$theta
result$coefficients
summary(result)
```

```
#plot the estimated single index function curve
plot_si(result)
```

---

plot_si	<i>Function that plot fitted curve for the unknown univariate function for single index term</i>
---------	--

---

### Description

Function that plot fitted curve for the unknown univariate function for single index term

### Usage

```
plot_si(
  x,
  family = gaussian(),
  ylab = "mean",
  yscale = NULL,
  plot_data = FALSE
)
```

### Arguments

x	the gam/gplism fitted object
family	default is gaussian()
ylab	y label
yscale	scale of y
plot_data	controls whether to plot the data as points

### Value

NULL single-index plot

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Predict.matrix.tr.smooth	<i>prediction method function for the tr smooth class</i>
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### Description

prediction method function for the tr smooth class

### Usage

```
Predict.matrix.tr.smooth(object, data)
```

**Arguments**

object            smooth object for gam class  
data              the new data to predict on '

**Value**

X the prediction matrix

---

`print.summary.gplsim`    *Print Summary function of gplsim object*

---

**Description**

Print Summary function of gplsim object

**Usage**

```
## S3 method for class 'summary.gplsim'  
print(  
  x,  
  digits = max(5, getOption("digits") - 3),  
  signif.stars = getOption("show.signif.stars"),  
  ...  
)
```

**Arguments**

x                    the gam/gplism fitted object  
digits               controls number of digits printed in output.  
signif.stars        should significance stars be printed alongside output.  
...                   optional arguments

**Value**

summarized object with nice format



---

si *An internal function to optimization and fitting. Don't use it solely.*

---

### Description

An internal function to optimization and fitting. Don't use it solely.

### Usage

```
si(  
  alpha,  
  y,  
  x,  
  z,  
  opt = TRUE,  
  smooth_selection,  
  fam,  
  bs = "ps",  
  fx = FALSE,  
  scale = scale,  
  ...  
)
```

### Arguments

alpha	single-index coefficients
y	Response variable, should be a vector.
x	Single index covariates.
z	Partially linear covariates.
opt	see ?gplsim
smooth_selection	see ?gplsim
fam	see ?gplsim
bs	see ?gplsim
fx	see ?gplsim
scale	see ?gplsim
...	includes optional arguments user can pass to <code>mgcv::gam</code> or <code>glm</code> , such as <code>k</code> , which is the dimension of the basis of the smooth term and <code>m</code> , which is the order of the penalty for the smooth term

### Value

b fitted gam object

---

```
smooth.construct.tr.smooth.spec
    supporting function to make tr smooth
```

---

**Description**

supporting function to make tr smooth

**Usage**

```
smooth.construct.tr.smooth.spec(object, data, knots)
```

**Arguments**

object	smooth object for gam class
data	the new data to predict on
knots	knots

**Value**

tr smooth object

---

```
summary.gplsim    Summary function of gplsim object
```

---

**Description**

Summary function of gplsim object

**Usage**

```
## S3 method for class 'gplsim'
summary(object, ...)
```

**Arguments**

object	the gam/gplism fitted object
...	optional arguments

**Value**

gplsim\_obj a list of summary information for a fitted gplsim object, which extends on gam object.

# Index

## \* datasets

air, [3](#)

add\_sim\_bound, [2](#)

air, [3](#)

generate\_data, [4](#)

gplsim, [4](#)

plot\_si, [7](#)

Predict.matrix.tr.smooth, [7](#)

print.summary.gplsim, [8](#)

si, [9](#)

smooth.construct.tr.smooth.spec, [10](#)

summary.gplsim, [10](#)